











## Internship on Robotic Process Automation

**Description:** Robotics and embedded systems are two fields that are closely related and have become increasingly important in recent years. Both areas involve the integration of hardware and software to create systems that can interact with the physical world. In this response, we will provide an overview of robotics and embedded systems, their applications, and some challenges associated with developing these technologies.























### Key Feature:

 Robotics	 Mechatronics	 IOT
 Embedded System	 Robotics	 Sensors, Safety and
 Automation Systems, programming robotic systems	 Fundamentals of Robot Programming	 Ethics
		 Project Development

**Result:** Participants will be able to

- ✓ Describe how sensors, microcontrollers, and servo motor's function and how they are implemented.
- ✓ Select Robots, Controller, Sensors and Actuators based on the application and technical specifications.
- ✓ Develop numerous servo motor-based robot projects using Arduino programming and excellent embedded system skills.
- ✓ Analyse the Arduino code used in other projects and determine what the code's function is.
- ✓ Relate various scenarios in which the sensors could be used.

### What will you learn:

- |   |  |
|---|--|
|  Embedded System   |  PCB Designing and fabrication                  |
|  Introduction of Electronic components   |  Making and Programming Line follower robot     |
|  Types of sensors  |  Making and Programming Wall follower robot     |
|  Modules   |  Making and Programming Edge Avoider robot      |
|  Types of Motors and working Principle   |  Making and Programming Obstacle Avoiding robot |
|  Microprocessor and Microcontroller  |  Bluetooth controlled robot                     |
|  Architecture of microcontroller   |  Wi-Fi based remote controlled robot            |
|  Atmega328P  |  PS2 controlled robot                           |
|  Embedded C language   |  NRF based robot                                |
|  Introduction to Arduino IDE   |  Camera surveillance robot                      |
|  Interfacing of all sensors and components used in robotics and embedded System. |  |
|  Communication devices e.g., Bluetooth, Wi-Fi, nRF, PS2 controller               |  |